## Ostrogradsij's theorem

Implications on modified gravity theories

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## Overview

- 1. Why modified theories of gravity?
- 2. Ostrogradskij's theorem
- 3. Horndeski Theories
- 4. Beyond Horndeski

## What is Einstein's theory of gravity?

$$G_{\mu\nu}=8\pi GT_{\mu\nu}$$

- Unchanged since its formulation
- Very well tested in numerous experiments
- It is the gravity theory used for ΛCDM Cosmology
- Field Theory (admits Lagrangian Formulation)

## Why search for alternative theories?

#### ΛCDM paradigm assumes infation:

- Dark Energy ( $\sim$  96% of energy has so far only been detected gravitationally!)
- Fine tuning

Easy solution: a field theory that doesn't require Dark Energy!
Actually, it's not so easy.

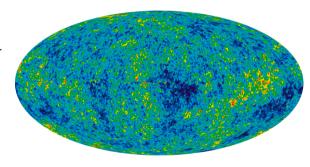


Figure: CMB temperature fluctuations acquired with WMAP

### Classical case

Classically we deal with  $L = L(q, \dot{q})$ 

$$\frac{\partial L}{\partial q} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}} = 0$$

If the Lagrangian is nondegenerate and we define  $Q \coloneqq q$  and  $P \coloneqq rac{\partial L}{\partial \dot{q}}$ 

$$H(Q, P) = Pv(Q, P) - L(Q, v(Q, P))$$

When the Lagrangian has no explicit time dependence, H is also the associated conserved quantity (i.e. **energy**)

## Higher Derivatives

Higher derivative dependence:  $L = L(q, \dot{q}, \ddot{q})$ 

$$\frac{\partial L}{\partial q} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}} + \frac{d^2}{dt^2} \frac{\partial L}{\partial \ddot{q}} = 0$$

$$g(t) = Q(t, q_0, \dot{q}_0, \ddot{q}_0, \ddot{q}_0)$$

Four pieces of initial value data means four canonical coordinates:

$$Q_1 := q$$
  $P_1 := \frac{\partial L}{\partial \dot{q}} - \frac{d}{dt} \frac{\partial L}{\partial \ddot{q}}$   $Q_2 := \dot{q}$   $P_2 := \frac{\partial L}{\partial \ddot{q}}$ 

## Higher Derivatives

Nondegeneracy implies that we can invert phase space transformation to solve for  $\ddot{q}$ 

$$\exists a(Q_1, Q_2, P_1): \frac{\partial L}{\partial \ddot{a}}|_{\ddot{q}=a}=P_2$$

$$H(Q_1, Q_2, P_1, P_2) = P_1Q_2 + P_2a(Q_1, Q_2, P_2) - L(Q_1, Q_2, a(Q_1, Q_2, P_2))$$

Again, when the Lagrangian has no explicit dependence on time, this is the energy of the system, but this time it is **linear** in  $P_1$ !

## Example: the free particle

$$L=rac{\dot{q}^2}{2}+rac{\ddot{q}^2}{2}$$
  $Q_1=q$   $P_1=\dot{q}-rac{\ddot{q}}{2}$   $Q_2=\dot{q}$   $P_2\ddot{q}$   $P_2\ddot{q}$   $P_1=\dot{q}-\ddot{q}$   $P_2\ddot{q}$   $P_2\ddot{q}$   $P_1=\dot{q}-\ddot{q}$   $P_2\ddot{q}$   $P_1=\dot{q}-\ddot{q}$   $P_2\ddot{q}$   $P_1=\dot{q}-\ddot{q}$   $P_2\ddot{q}$   $P_1=\dot{q}-\ddot{q}$   $P_2\ddot{q}$   $P_1=\dot{q}-\ddot{q}$   $P_2\ddot{q}$   $P_1=\dot{q}-\ddot{q}$   $P_1=\dot{q}-\ddot{q}$ 

It is straightforward to prove that adding higher order terms in the Lagrangian makes thing worse!

#### General Case

#### Theorem (Ostrogradskij)

Every system described by a nondegenerate Lagrangian which depends upon more than one time derivative (in such a way that the dependence cannot be eliminated by partial integration) is instable.

Only way out (so far): violating the nondegeneracy assumption

# Horndeski's theory ('72)

$$\mathcal{L} = \mathcal{L}(g_{ij}; g_{ij,k}; g_{ij,kh}; \phi; \phi_{,i})$$

Generate the following Euler-Lagrange equations

$$E^{ij}(\mathcal{L}) = \frac{\partial}{\partial x^{k}} \left[ \frac{\partial \mathcal{L}}{\partial g_{ij,k}} - \frac{\partial}{\partial x^{h}} \left( \frac{\partial \mathcal{L}}{\partial g_{ij,hk}} \right) \right] - \frac{\partial \mathcal{L}}{\partial g_{ij}}$$
$$E(\mathcal{L}) = \frac{\partial}{\partial x^{k}} \left[ \frac{\partial \mathcal{L}}{\partial \phi_{,k}} \right] - \frac{\partial \mathcal{L}}{\partial \phi}$$

- Can suffer Ostrogradskij instability
- · Find constraints such that field equations are second order

## Horndeski's theory '72

$$\mathcal{L} = \beta_1 \mathcal{L}_1 + \beta_2 \mathcal{L}_2 + \beta_3 \mathcal{L}_3 + \eta \mathcal{L}_4 + c \mathcal{L}_5$$

$$\mathcal{L}_{1} = \sqrt{g}(R^{2} - 4R_{ij}R^{ij} + R_{ijkl}R^{ijkl}), \qquad \mathcal{L}_{2} = \sqrt{g}G^{ij}\phi_{,i}\phi_{,j}$$

$$\mathcal{L}_{3} = \sqrt{g}R, \qquad \mathcal{L}_{4} = \sqrt{g}, \qquad \mathcal{L}_{5} = \sqrt{g}*R^{ij}_{kh}R^{kh}_{ij}$$

- ullet  $E^{ij}$  and E are at most second order in  $g_{ij}$  and  $\phi$
- Does not suffer from instability

## Horndeski's theory '74

- Previous treatment covered only a restricted number of cases
- What happens for a general Lagrangian density?

$$\mathcal{L} = \mathcal{L}(g_{ij}; g_{ij,i_1}; \ldots; g_{ij,i_1\ldots i_p}; \phi; \phi_{,i_1}; \ldots; \phi_{,i_1\ldots i_q})$$

Keep the requirement for the E-L equations to be at most of second order

$$\Rightarrow \mathcal{L} = \mathcal{L}(g_{ij}; g_{ij,i_1}; g_{ij,i_1i_2}; \phi; \phi_{,i_1}; \phi_{,i_1i_2})$$

#### Horndeski theories

#### **GENERALIZED GALILEONS:**

$$\mathcal{L} = G_{2}(\phi, X) - G_{3}(\phi, X) \Box \phi + G_{4}(\phi, X)R + G_{4X}[(\Box \phi)^{2} - \phi^{\mu\nu}\phi_{\mu\nu}] + G_{5}(\phi, X)G^{\mu\nu}\phi_{\mu\nu} - \frac{G_{5X}}{6}[(\Box \phi)^{3} - 3\Box \phi\phi^{\mu\nu}\phi_{\mu\nu} + 2\phi_{\mu\nu}\phi^{\nu\lambda}\phi^{\mu}_{\lambda}]$$

Where

$$X := \nabla_{\mu} \phi \nabla^{\mu} \phi \qquad \phi_{\mu\nu} := \nabla_{\mu} \nabla_{\nu} \phi$$

BUT, there is more...

## Beyond Horndeski

Main problem is Ostrogradskij, NOT the order of E-L equations

$$L = \frac{a}{2}\ddot{\phi}^2 + b\ddot{\phi}\dot{q} + \frac{c}{2}\dot{q}^2 + \frac{1}{2}\dot{\phi}^2 - \frac{1}{2}\phi^2 - \frac{1}{2}\phi^2$$

- Higher order E-L equations
- Ostrogradski ghosts

However, if kinetic matrix is degenerate, the system is **free from Ostrogradski ghosts!** ⇒ **DHOST Theories** 

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# The End