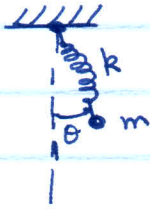


7-29)



$$\begin{cases} x = l \sin \theta \\ y = -l \cos \theta + \frac{at^2}{2} \end{cases} \Rightarrow \begin{cases} \dot{x} = \dot{l} \sin \theta + l \cos \theta \dot{\theta} \\ \dot{y} = -\dot{l} \cos \theta + l \sin \theta \dot{\theta} + at \end{cases}$$

$$T = \frac{m}{2} (\dot{x}^2 + \dot{y}^2)$$

$$U = mgy + \frac{k}{2} (l-b)^2$$

(a) Thus, $L = T - U$

$$= \frac{m}{2} \left\{ \dot{l}^2 + l^2 \dot{\theta}^2 + 2at(l\dot{\theta} \sin \theta - \dot{l} \cos \theta) + a^2 t^2 \right\} - mgy - \frac{k}{2} (l-b)^2$$

$$= \frac{m}{2} \left\{ \dot{l}^2 + l^2 \dot{\theta}^2 + 2at(l\dot{\theta} \sin \theta - \dot{l} \cos \theta) + a^2 t^2 \right\} + mg(l \cos \theta - \frac{at^2}{2}) - \frac{k}{2} (l-b)^2$$

The Euler-Lagrange equations for l, θ $\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_i} \right) = \frac{\partial L}{\partial q_i}$ become:

$$\underline{l}: \quad \frac{d}{dt} (m\dot{l} - mat \cos \theta) = m l \dot{\theta}^2 + mat \dot{\theta} \sin \theta + mg \cos \theta - k(l-b)$$

$$\underline{\theta}: \quad \frac{d}{dt} (m l^2 \dot{\theta} + mat l \sin \theta) = mat l \dot{\theta} \cos \theta + mat \dot{l} \sin \theta - mgl \sin \theta$$

(b) Due to the explicit time dependence in the transformation equations we need to be careful and not simply use $H = T + U$.

$$p_l = m\dot{l} - mat \cos \theta \quad \Rightarrow \quad \dot{l} = \frac{p_l}{m} + at \cos \theta \quad \Rightarrow \quad p_l \dot{l} = \frac{p_l^2}{m} + p_l at \cos \theta$$

$$p_\theta = m l^2 \dot{\theta} + mat l \sin \theta \quad \Rightarrow \quad \dot{\theta} = \frac{p_\theta}{m l^2} - \frac{at \sin \theta}{l} \quad \Rightarrow \quad p_\theta \dot{\theta} = \frac{p_\theta^2}{m l^2} - \frac{p_\theta at \sin \theta}{l}$$

Now we can write

$$H = p_l \dot{l} + p_\theta \dot{\theta} - L = \frac{p_l^2}{m} + p_l at \cos \theta + \frac{p_\theta^2}{m l^2} - \frac{p_\theta at \sin \theta}{l} - L$$

7-29, p.2)
$$H = \frac{p_\ell^2}{m} + p_\theta a t \cos \theta + \frac{p_\theta^2}{m \ell^2} - p_\theta \frac{a t \sin \theta}{\ell}$$

$$- \frac{m}{2} \left\{ \left(\frac{p_\ell}{m} + a t \cos \theta \right)^2 + \ell^2 \left(\frac{p_\theta}{m \ell^2} - \frac{a t \sin \theta}{\ell} \right)^2 \right.$$

$$\left. + 2 a t \left(\ell \left(\frac{p_\theta}{m \ell^2} - \frac{a t \sin \theta}{\ell} \right) \sin \theta - \left(\frac{p_\ell}{m} + a t \cos \theta \right) \cos \theta \right) + a^2 t^2 \right\}$$

$$- m g \left(\ell \cos \theta - \frac{a t^2}{2} \right) + \frac{k}{2} (\ell - b)^2$$

$$= \frac{p_\ell^2}{2m} - \frac{m}{2} a^2 t^2 \cos^2 \theta + \frac{p_\theta^2}{2m \ell^2} - \frac{m}{2} a^2 t^2 \sin^2 \theta$$

$$- \frac{a t p_\theta \sin \theta}{\ell} + m a^2 t^2 \sin^2 \theta + a t p_\theta \cos \theta + m a^2 t^2 \cos^2 \theta - \frac{m}{2} a^2 t^2$$

$$- m g \left(\ell \cos \theta - \frac{a t^2}{2} \right) + \frac{k}{2} (\ell - b)^2$$

$$= \frac{p_\ell^2}{2m} + \frac{p_\theta^2}{2m \ell^2} + a t p_\theta \cos \theta - \frac{a t p_\theta \sin \theta}{\ell} - m g \ell \cos \theta + \frac{m g a t^2}{2} + \frac{k}{2} (\ell - b)^2$$

Now we can get equations for $\theta, \ell, p_\theta, p_\ell$:

$$\dot{\theta} = \frac{\partial H}{\partial p_\theta} = \frac{p_\theta}{m \ell^2} - \frac{a t \sin \theta}{\ell} \quad \text{and} \quad \dot{\ell} = \frac{\partial H}{\partial p_\ell} = \frac{p_\ell}{m} + a t \cos \theta$$

Similarly, using $\dot{p}_i = -\frac{\partial H}{\partial q_i}$ we get

$$\dot{p}_\theta = a t p_\theta \sin \theta + \frac{a t p_\theta \cos \theta}{\ell} - m g \ell \sin \theta \quad \text{and}$$

$$\dot{p}_\ell = \frac{p_\theta^2}{m \ell^3} - \frac{a t p_\theta \sin \theta}{\ell^2} + m g \cos \theta - k (\ell - b)$$

- (c) For small oscillations we can set $\cos \theta \approx 1$ and $\sin \theta \approx \theta$ to get from the Euler-Lagrange equations for ℓ
- l-eqn: $\ddot{\ell} - a \approx -g - \frac{k}{m} (\ell - b)$ [neglecting $\theta \dot{\theta}, \dot{\theta}^2$ terms]
- i.e., $\ddot{\ell} + \left(\frac{k}{m}\right) \ell \approx (g+a) + \left(\frac{k}{m}\right) b$. Set $\omega = \sqrt{\frac{k}{m}}$ and this is the angular frequency of oscillations.
- $T_\ell = 2\pi/\omega = 2\pi \sqrt{m/k}$.
- Similarly, for θ we get $\ddot{\theta} + \frac{a}{\ell} \sin \theta \approx -g \sin \theta$
- i.e., $\ddot{\theta} + \frac{(g+a)}{\ell} \theta \approx 0$. Thus, $T_\theta \approx 2\pi \sqrt{\ell/(g+a)}$.